# Properties of the Support of Solutions of a Class of 2-Dimensional Nonlinear Evolution Equations 

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Abstract. In this work we consider equations of the form

$$
\partial_{t} u+P(D) u+u^{l} \partial_{x} u=0
$$

where $P(D)$ is a two-dimensional differential operator, and $l \in \mathbb{N}$. We prove that if $u$ is a sufficiently smooth solution of the equation, such that $\operatorname{supp} u(0), \operatorname{supp} u(T) \subset[-B, B] \times[-B, B]$ for some $B>0$, then there exists $R_{0}>0$ such that $\operatorname{supp} u(t) \subset\left[-R_{0}, R_{0}\right] \times\left[-R_{0}, R_{0}\right]$ for every $t \in[0, T]$.

Keywords: Nonlinear evolution equations, weighted Sobolev spaces, Carleman estimates.

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## Propiedades del soporte de soluciones de una clase de ecuaciones de evolución no lineales en dos dimensiones

Resumen. En este trabajo consideramos ecuaciones de la forma

$$
\partial_{t} u+P(D) u+u^{l} \partial_{x} u=0
$$

donde $P(D)$ es un operador diferencial en dos dimensiones, y $l \in \mathbb{N}$. Probamos que si $u$ es una solución suficientemente suave de la ecuación, tal que $\operatorname{supp} u(0), \operatorname{supp} u(T) \subset[-B, B] \times[-B, B]$ para algún $B>0$, entonces existe $R_{0}>0$ tal que $\operatorname{supp} u(t) \subset\left[-R_{0}, R_{0}\right] \times\left[-R_{0}, R_{0}\right]$ para todo $t \in[0, T]$.
Palabras clave: Ecuaciones de evolución no lineales, espacios de Sobolev con peso, estimativos Carleman.

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## 1. Introduction

In this note we study nonlinear evolution equations of the form

$$
\begin{equation*}
\partial_{t} u+P(D) u+u^{l} \partial_{x} u=0 \tag{1}
\end{equation*}
$$

where $P(D) u:=\sum_{j=0}^{n} \sum_{j^{\prime}=0}^{n-j} a_{j j^{\prime}} \partial_{x}^{j} \partial_{y}^{j^{\prime}} u, a_{j j^{\prime}} \in \mathbb{C}$, with $a_{00}=0$, and $n \in\{1,2,3, \ldots\}$. Some well-known models belong to the class defined by (1) (see [1] and [17]). For instance, the Zakharov-Kuznetsov (ZK) equation, for which

$$
P(D) u=\partial_{x}^{3} u+\partial_{x} \partial_{y}^{2} u
$$

and $l=1$. The ZK equation is a bidimensional generalization of the Korteweg-de Vries $(\mathrm{KdV})$ equation which is a mathematical model to describe the propagation of nonlinear ion-acoustic waves in magnetized plasma ([18]). Some aspects concerning the behavior of the solutions of the ZK equation has been studied in [3], [7], [13], [12], [14].
The class defined by (1) also includes the two dimensional Kawahara equation, for which

$$
P(D) u=\alpha \partial_{x} u+\partial_{x}^{3} u+\partial_{x} \partial_{y}^{2} u-\partial_{x}^{5} u
$$

where $\alpha$ is equal to 1 or 0 (see [11] and references therein), and the Kawahara-Burgers equation (see [10] and references therein). Both of them are perturbations of the (ZK) equation.
In 2011, Bustamante, Isaza and Mejía, in [6], proved that if the support of a sufficiently smooth solution of the ZK equation $u$ is contained in a square at two different times, then the solution must vanish. To obtain this, they first prove that if the hypotheses mentioned are satisfied, then exists a square in which the support of $u$ is contained for all times. Then, using a result obtained by Panthee in [16], they manage to prove that $u=0$.

Our main result is a generalization of the one concerning the support of the solutions of the ZK equation achieved in [6]. Specifically, we extend it to the general case of $\mathbb{R}^{2}$, showed in equation (1), and we present it in detail in the following theorem.

Theorem 1.1. Let $n \in \mathbb{N}$, and $P(D)$ the operator defined by

$$
P(D) u:=\sum_{j=0}^{n} \sum_{j^{\prime}=0}^{n-j} a_{j j^{\prime}} \partial_{x}^{j} \partial_{y}^{j^{\prime}} u, \quad \text { with } a_{j j^{\prime}} \in \mathbb{C}, \text { and } a_{00}=0
$$

Suppose that $u \in C\left([0, T] ; H^{s}\left(\mathbb{R}^{2}\right)\right) \cap L^{\infty}\left([0, T] ; L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)\right) \cap C^{1}\left([0, T] ; L^{2}\left(\mathbb{R}^{2}\right)\right)$, $s>n$ (in any case $s>3$ ) for every $\beta>0$, and that $u$ is a solution of (1) in $[0, T] \times \mathbb{R}^{2}$. If $\operatorname{supp} u(0)$ and $\operatorname{supp} u(T)$ are contained in $[-B, B] \times[-B, B]$ for some $B>0$, then there exists $R_{0}>0$ such that $\operatorname{supp} u(t) \subset\left[-R_{0}, R_{0}\right] \times\left[-R_{0}, R_{0}\right]$ for every $t \in[0, T]$.
(See the definition of the space $L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)$ below).
In the proof of Theorem 1.1 we follow the ideas of Bustamante, Isaza and Mejía in [6] for the ZK equation, and Kenig, Ponce and Vega in [9] for the generalized Korteweg-de Vries (KdV) equation.

It is possible to extend the result of Theorem 1.1 to the general case where $P$ is a polynomial with $n$ spatial variables. This would allow to study dispersive equations in higher dimensions. In particular, the use of a result like this, together with the techniques developed by Bourgain in [4], would permit to obtain unique continuation principles to dispersive models in high spatial dimensions.

This paper is organized as follows: in Section 2, we present an interpolation result which allows to obtain estimates for the spatial derivatives of a function with certain regularity. It is at this point where the restriction $s>3$ is needed. In Section 3, we prove a Carleman estimate of $L^{2}-L^{2}$ type. Finally, in Section 4, we establish Theorem 1.1.
Throughout this article the symbol $\hat{f}$ will denote the spatial Fourier transform of a function $f$ in $\mathbb{R}^{2}$. We say that a function $f$ belongs to the weighted $L^{2}$ space, $L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)$, if it is true that $e^{\beta|\cdot x|} e^{\beta|\cdot y|} f \in L^{2}\left(\mathbb{R}^{2}\right)$; i.e. if

$$
\left(\int_{\mathbb{R}^{2}}|f(x, y)|^{2} e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)^{1 / 2}<\infty .
$$

In a similar way the spaces $L^{2}\left(e^{2 \beta x} d x d y\right)$ and $L^{2}\left(e^{2 \beta y} d x d y\right)$ are defined.
With respect to the weighted Sobolev space $H^{n}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)$, that we use in Theorem 3.2 , we say that a function $f$ belongs to this space if $e^{\beta|\cdot x|} e^{\beta|\cdot y|} f \in H^{n}\left(\mathbb{R}^{2}\right)$. This is true if

$$
\left(\int_{\mathbb{R}^{2}}\left(1+\xi^{2}+\tau^{2}\right)^{n}\left|\left(e^{\beta|\cdot x|} e^{\beta|\cdot y|} f\right)^{\wedge}(\xi, \tau)\right|^{2} d \xi d \tau\right)^{1 / 2}<\infty
$$

Besides, the letter $C$ will denote diverse positive constants which may change from line to line and depend on parameters which are clearly established in each case.

## 2. Preliminary Estimates in Weighted Sobolev Spaces

The following lemma is an interpolation result and can be proved using the Hadamard Three-lines theorem in a similar way than Lemma 4 in [15]. We omit its proof here.

Lemma 2.1. For $s>0$ and $\beta>0$ let $f \in H^{s}\left(\mathbb{R}^{2}\right) \cap L^{2}\left(e^{2 \beta x} d x d y\right)$. Then, for $\theta \in[0,1]$,

$$
\begin{equation*}
\left\|J^{s \theta}\left(e^{((1-\theta) \beta x)} f\right)\right\|_{L^{2}} \leq C\left\|J^{s} f\right\|_{L^{2}}^{\theta}\left\|e^{\beta x} f\right\|_{L^{2}}^{1-\theta}, \tag{2}
\end{equation*}
$$

where $\left[J^{s} f\right]^{\wedge}(\xi):=\left(1+|\xi|^{2}\right)^{s / 2} \hat{f}(\xi)$ and $C=C(s, \beta)$. Similarly, if $f \in H^{s}\left(\mathbb{R}^{2}\right) \cap$ $L^{2}\left(e^{2 \beta y} d x d y\right)$, then, for $\theta \in[0,1]$,

$$
\begin{equation*}
\left\|J^{s \theta}\left(e^{(1-\theta) \beta y} f\right)\right\|_{L^{2}} \leq C\left\|J^{s} f\right\|_{L^{2}}^{\theta}\left\|e^{\beta y} f\right\|_{L^{2}}^{1-\theta} . \tag{3}
\end{equation*}
$$

Remark 2.2. If $u \in C\left([0, T] ; H^{s}\left(\mathbb{R}^{2}\right)\right) \cap L^{\infty}\left([0, T] ; L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)\right)$ for every $\beta>0$, with $s>3$, it is easy to see that there exists $C_{1}>0$ and $C_{2}>0$ independent of $t$, such that

$$
\begin{equation*}
\left|\partial_{x} u(t)(x, y)\right| \leq C_{1} e^{-x}, \tag{4}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\partial_{y} u(t)(x, y)\right| \leq C_{2} e^{-y} \tag{5}
\end{equation*}
$$

for every $t \in[0, T]$. In fact, using the Sobolev embedding $H^{2}\left(\mathbb{R}^{2}\right) \subset L^{\infty}\left(\mathbb{R}^{2}\right)$ we have that there exists $C>0$ such that

$$
\begin{aligned}
\left\|e^{x} \partial_{x} u(t)\right\|_{L^{\infty}\left(\mathbb{R}^{2}\right)} & \leq C\left\|e^{x} \partial_{x} u(t)\right\|_{H^{2}\left(\mathbb{R}^{2}\right)}=C\left\|\partial_{x}\left(e^{x} u(t)\right)-e^{x} u(t)\right\|_{H^{2}\left(\mathbb{R}^{2}\right)} \\
& \leq C\left[\left\|e^{x} u(t)\right\|_{H^{2}\left(\mathbb{R}^{2}\right)}+\left\|\partial_{x}\left(e^{x} u(t)\right)\right\|_{H^{2}\left(\mathbb{R}^{2}\right)}\right] \\
& =C\left[\left\|J^{2}\left(e^{x} u(t)\right)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}+\left\|J^{2}\left(\partial_{x}\left(e^{x} u(t)\right)\right)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}\right] \\
& \leq C\left[\left\|J^{2}\left(e^{x} u(t)\right)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}+\left\|J^{3}\left(e^{x} u(t)\right)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}\right]
\end{aligned}
$$

Since $s>3$, we can use Lemma 2.1 taking $\theta:=3 / s$ and $\beta:=(1-3 / s)^{-1}$ to conclude, by inequality (2), that

$$
\left\|J^{3}\left(e^{x} u(t)\right)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)} \leq C\left\|J^{s} u(t)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}^{3 / s}\left\|e^{(1-3 / s)^{-1} x} u(t)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}^{1-3 / s} \leq C_{1}
$$

and

$$
\left\|J^{2}\left(e^{x}\right) u(t)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)} \leq\left\|J^{3}\left(e^{x} u(t)\right)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)} \leq C_{1}
$$

Thus, for a.e. $(x, y) \in \mathbb{R}^{2}$,

$$
\left|e^{x} \partial_{x} u(t)(x, y)\right| \leq C_{1}, \quad\left|\partial_{x} u(t)(x, y)\right| \leq C_{1} e^{-x}
$$

which is (4). Obviously, (5) follows in an analogous way, using (3) instead of (2).

## 3. Estimates of the Carleman Type

The following lemma is used in the proof of the Carleman estimates (Theorem 3.2) and it justifies the formal computation of the temporal derivative of $\widehat{e^{\lambda x}(t)}(\xi)$ and $\widehat{e^{\lambda y}(t)}(\xi)$. Its proof is taken from [6] and it is presented here for the sake of completeness.
Lemma 3.1. Let $w \in C^{1}\left([0, T] ; L^{2}\left(\mathbb{R}^{2}\right)\right)$ be a function such that for all $\beta>$ $0, \quad w$ is bounded from $[0, T]$ with values in $L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)$ and $w^{\prime} \in$ $L^{1}\left([0, T] ; L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)\right)$. Then, for all $\lambda \in \mathbb{R}$ and all $\xi=\left(\xi_{1}, \xi_{2}\right) \in \mathbb{R}^{2}$, the functions $t \mapsto \widehat{e^{\lambda x} w(t)}(\xi)$ and $t \mapsto e^{\widehat{\lambda y} w(t)}(\xi)$ are absolutely continuous in $[0, T]$ with derivatives $e^{\widehat{\lambda x} w^{\prime}}(t)(\xi)$ and $e^{\widehat{\lambda y} w^{\prime}(t)}(\xi)$ a.e. $t \in[0, T]$, respectively.

Proof. By symmetry, it is sufficient to prove the lemma only for the weight $e^{\lambda x}$. It is easy to see that for all $t \in[0, T]$ and $\lambda \in \mathbb{R}, e^{\lambda x} w(t) \in L^{1}\left(\mathbb{R}^{2}\right)$, and also that $e^{\lambda x} w^{\prime} \in$ $L^{1}\left(\mathbb{R}^{2} \times[0, T]\right)$ for all $\lambda \in \mathbb{R}$. For $R>0$, let $\chi_{R}$ be the characteristic function of the square $[-R, R] \times[-R, R]$. Since $w \in C^{1}\left([0, T] ; L^{2}\left(\mathbb{R}^{2}\right)\right)$,

$$
\begin{equation*}
t \mapsto \int_{\mathbb{R}^{2}} e^{-i x \xi_{1}} e^{-i y \xi_{2}} e^{\lambda x} \chi_{R}(x, y) w(t)(x, y) d x d y=\left\langle w(t), e^{i x \xi_{1}} e^{i y \xi_{2}} e^{\lambda x} \chi_{R}\right\rangle_{L^{2}\left(\mathbb{R}^{2}\right)} \tag{6}
\end{equation*}
$$

defines a $C^{1}$ function of the variable $t$ with derivative given by

$$
t \mapsto\left\langle w^{\prime}(t), e^{i x \xi_{1}} e^{i y \xi_{2}} e^{\lambda x} \chi_{R}\right\rangle_{L^{2}\left(\mathbb{R}^{2}\right)}
$$

and in consequence

$$
\begin{aligned}
\int_{\mathbb{R}^{2}} e^{-i x \xi_{1}} e^{-i y \xi_{2}} e^{\lambda x} & \chi_{R}(x, y) w(t)(x, y) d x d y
\end{aligned}=\left\{\begin{aligned}
=\int_{0}^{t} \int_{\mathbb{R}^{2}} e^{-i x \xi_{1}} e^{-i y \xi_{2}} e^{\lambda x} & \chi_{R}(x, y) w^{\prime}(\tau)(x, y) d x d y d \tau \\
& +\int_{\mathbb{R}^{2}} e^{-i x \xi_{1}} e^{-i y \xi_{2}} e^{\lambda x} \chi_{R}(x, y) w(0)(x, y) d x d y
\end{aligned}\right.
$$

The lemma follows from the former equality by an application of the Lebesgue Dominated Convergence Theorem.

The following theorem is the main result of this section. It is a Carleman estimate of $L^{2}-L^{2}$ type and it is crucial in the proof of Theorem 1.1.

Theorem 3.2. For $n \in \mathbb{N}$, let $w \in C\left([0, T] ; H^{n}\left(\mathbb{R}^{2}\right)\right) \cap C^{1}\left([0, T] ; L^{2}\left(\mathbb{R}^{2}\right)\right)$, be a function such that for all $\beta>0$,
(i) $w$ is bounded from $[0, T]$ with values in $H^{n}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)$, and
(ii) $w^{\prime} \in L^{1}\left([0, T] ; L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)\right)$.

Then, for all $\lambda \neq 0$,

$$
\left\|e^{\lambda x} w\right\|_{L^{2}\left(\mathbb{R}^{2}\right)} \leq\left\|e^{\lambda x} w(0)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}+\left\|e^{\lambda x} w(T)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}+\left\|e^{\lambda x}\left(w^{\prime}+P(D) w\right)\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}
$$

where $P(D)$ is the operator defined by

$$
P(D) u:=\sum_{j=0}^{n} \sum_{j^{\prime}=0}^{n-j} a_{j j^{\prime}} \partial_{x}^{j} \partial_{y}^{j^{\prime}} u
$$

with $a_{j j^{\prime}} \in \mathbb{C}$ for $j, j^{\prime}=0, \ldots, n$, and $a_{00}=0$.
A similar estimate also holds with $y$ instead of $x$ in the exponents.

Proof. Let us define $g(t):=e^{\lambda x} w(t)$ and $h(t):=e^{\lambda x}\left(w^{\prime}(t)+P(D) w(t)\right)$. Taking into account that we can write

$$
P(D) w=\sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \partial_{x}^{j} w\right]
$$

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we have that

$$
\begin{aligned}
P(D) w & =\sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \partial_{x}^{j}\left(g e^{-\lambda x}\right)\right] \\
& =\sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \sum_{k=0}^{j}\binom{j}{k} \partial_{x}^{j-k} g \partial_{x}^{k} e^{-\lambda x}\right] \\
& =e^{-\lambda x} \sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \sum_{k=0}^{j}(-\lambda)^{k}\binom{j}{k} \partial_{x}^{j-k} g\right] \\
& =e^{-\lambda x} \sum_{j^{\prime}=0}^{n} \sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \partial_{y}^{j^{\prime}}\left[\sum_{k=0}^{j}(-\lambda)^{k}\binom{j}{k} \partial_{x}^{j-k} g\right] .
\end{aligned}
$$

This way,

$$
h(t)=e^{\lambda x} w^{\prime}(t)+\sum_{j^{\prime}=0}^{n} \sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \partial_{y}^{j^{\prime}}\left[\sum_{k=0}^{j}(-\lambda)^{k}\binom{j}{k} \partial_{x}^{j-k} g\right] .
$$

Since $w(t) \in H^{n}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)$ for all $\beta>0, t \in[0, T]$, and $w^{\prime} \in L^{2}\left(e^{2 \beta|x|} e^{2 \beta|y|} d x d y\right)$ for all $\beta>0$ a.e. $t \in[0, T]$, by using the Cauchy-Schwarz inequality, it can be seen that $h(t) \in L^{1}\left(\mathbb{R}^{2}\right)$ a.e. $t \in[0, T]$. We take the spatial Fourier transform to $h$ and apply Lemma 3.1 to obtain

$$
\frac{d}{d t} \widehat{g(t)}(\xi)+\left[\sum_{j^{\prime}=0}^{n} \sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}}\left(i \xi_{2}\right)^{j^{\prime}} \sum_{k=0}^{j}(-\lambda)^{k}\binom{j}{k}\left(i \xi_{1}\right)^{j-k}\right] \widehat{g(t)}(\xi)=\widehat{h(t)}(\xi)
$$

a.e. $t \in[0, T]$, where $\xi \equiv\left(\xi_{1}, \xi_{2}\right)$. Taking into account that the expression between squared parentheses is a polynomial function of the variables $\xi_{1}$ and $\xi_{2}$, with complex coefficients, the former equality can be written in the way

$$
\begin{equation*}
\frac{d}{d t} \widehat{g(t)}(\xi)+\left[i m_{\lambda}(\xi)+a_{\lambda}(\xi)\right] \widehat{g(t)}(\xi)=\widehat{h(t)}(\xi) \quad \text { a.e. } t \in[0, T] \tag{7}
\end{equation*}
$$

where $m_{\lambda}$ and $a_{\lambda}$ are polynomial functions in $\mathbb{R}^{2}$. We do not show interest in the precise form of $m_{\lambda}(\xi)$ and $a_{\lambda}(\xi)$ because when we estimate $|\widehat{g(t)}(\xi)|$ we only use the fact that $m_{\lambda}(\xi) \in \mathbb{R}$ and $a_{\lambda}(\xi) \in \mathbb{R}$, considering two cases: $a_{\lambda}(\xi) \leq 0$ and $a_{\lambda}(\xi)>0$, as we can see below.
(i) When $a_{\lambda}(\xi) \leq 0$, we solve (7) integrating between 0 and $t$ to obtain

$$
\widehat{g(t)}(\xi)=e^{i m_{\lambda}(\xi) t} e^{a_{\lambda}(\xi) t} \widehat{g(0)}(\xi)+\int_{0}^{t} e^{i m_{\lambda}(\xi)(t-\tau)} e^{a_{\lambda}(\xi)(t-\tau)} \widehat{h(\tau)}(\xi) d \tau
$$

for every $t \in[0, T]$. Since $m_{\lambda}(\xi) \in \mathbb{R}$ and $a_{\lambda}(\xi) \leq 0$, we have that

$$
\left|e^{i m_{\lambda}(\xi) t}\right|=1, \quad\left|e^{i m_{\lambda}(\xi)(t-\tau)}\right|=1, \quad e^{a_{\lambda}(\xi) t} \in(0,1] \text { and } e^{a_{\lambda}(\xi)(t-\tau)} \in(0,1]
$$

for every $t \in[0, T]$ and each $\tau \in[0, t]$. Thus, in this case,

$$
\begin{equation*}
|\widehat{g(t)}(\xi)| \leq|\widehat{g(0)}(\xi)|+\int_{0}^{t}|\widehat{g(\tau)}(\xi) d \tau| \tag{8}
\end{equation*}
$$

for each $t \in[0, T]$.
(ii) When $a_{\lambda}(\xi)>0$, we solve (7) this time integrating between $t$ and $T$ to obtain

$$
\widehat{g(t)}(\xi)=e^{-i m_{\lambda}(\xi)(T-t)} e^{-a_{\lambda}(\xi)(T-t)} \widehat{g(T)}(\xi)+\int_{t}^{T} e^{-i m_{\lambda}(\xi)(\tau-t)} e^{-a_{\lambda}(\xi)(\tau-t)} \widehat{h(\tau)}(\xi) d \tau
$$

for every $t \in[0, T]$. Since $m_{\lambda}(\xi) \in \mathbb{R}$ and $a_{\lambda}(\xi)>0$, we have that

$$
\begin{gathered}
\left|e^{-i m_{\lambda}(\xi)(T-t)}\right|=1, \quad\left|e^{-i m_{\lambda}(\xi)(\tau-t)}\right|=1, \\
e^{-a_{\lambda}(\xi)(T-t)} \in(0,1] \quad \text { and } \quad e^{-a_{\lambda}(\xi)(\tau-t)} \in(0,1],
\end{gathered}
$$

for every $t \in[0, T]$ and each $\tau \in[t, \tau]$. Thus, in this case,

$$
\begin{equation*}
|\widehat{g(t)}(\xi)| \leq|\widehat{g(0)}(\xi)|+\int_{t}^{T}|\widehat{g(\tau)}(\xi) d \tau| \tag{9}
\end{equation*}
$$

for each $t \in[0, T]$.
From (8) and (9) we can conclude that, in any case, for every $t \in[0, T]$,

$$
|\widehat{g(t)}(\xi)| \leq|\widehat{g(0)}(\xi)|+|\widehat{g(T)}(\xi)|+\int_{0}^{T}|\widehat{h(\tau)}(\xi)| d \tau
$$

Hence, by Plancherel's Formula,

$$
\left\|e^{\lambda x} w\right\| \leq\left\|e^{\lambda x} w(0)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}+\left\|e^{\lambda x} w(T)\right\|_{L^{2}\left(\mathbb{R}^{2}\right)}+\left\|e^{\lambda x}\left(w^{\prime}+P w\right)\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}
$$

The proof of the estimate with the weight $e^{\lambda y}$ is similar.

## 4. Proof of Theorem 1.1

Let $\tilde{\phi} \in C^{\infty}(\mathbb{R})$ a non-decreasing function such that $\tilde{\phi}(x)=0$ for $x<0$, and $\tilde{\phi}(x)=1$ for $x>1$ and, for $R>B$, let $\phi(x) \equiv \phi_{R}(x):=\tilde{\phi}(x-R)$. We define $w \equiv w_{R}:=\phi(x) u$, and $v \equiv v_{R}:=\phi(y) u$. It is easy to check that $w$ and $v$ satisfy the hypotheses of Theorem 3.2. Taking into account that $w(0)=w(T)=0$, from Theorem 3.2, we conclude that, for every $\lambda \neq 0$,

$$
\begin{align*}
\left\|e^{\lambda x} w\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} & \leq\left\|e^{\lambda x}\left(w^{\prime}+P(D) w\right)\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} \\
& =\left\|e^{\lambda x}\left(\phi u^{\prime}+P(D) w\right)\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} . \tag{10}
\end{align*}
$$

As in the proof of Theorem 3.2, we take into account that

$$
P(D) w=\sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \partial_{x}^{j} w\right] .
$$

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Hence,

$$
\begin{aligned}
P(D) w & =P(D)(\phi u)=\sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \partial_{x}^{j}(\phi u)\right] \\
& =\sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \sum_{k=0}^{j}\binom{j}{k} \partial_{x}^{j-k} u \phi^{(k)}\right] \\
& =\phi \sum_{j^{\prime}=0}^{n} \partial_{y}^{j^{\prime}}\left[\sum_{j=0}^{n-j^{\prime}} a_{j j^{\prime}} \partial_{x}^{j} u\right]+\sum_{j^{\prime}=0}^{n-1} \partial_{y}^{j^{\prime}}\left[\sum_{j=1}^{n-j^{\prime}} a_{j j^{\prime}} \sum_{k=1}^{j}\binom{j}{k} \partial_{x}^{j-k} u \phi^{(k)}\right] \\
& =\phi P u+\sum_{j^{\prime}=0}^{n-1} \partial_{y}^{j^{\prime}}\left[\sum_{j=1}^{n-j^{\prime}} a_{j j^{\prime}} \sum_{k=1}^{j}\binom{j}{k} \partial_{x}^{j-k} u \phi^{(k)}\right]
\end{aligned}
$$

Therefore, from (10), and (1), we conclude that

$$
\left\|e^{\lambda x} w\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} \leq\left\|e^{\lambda x} \phi u^{l} \partial_{x} u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}+\left\|e^{\lambda x} F_{1 \phi, u}\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}
$$

where

$$
F_{1 \phi, u}:=\sum_{j^{\prime}=0}^{n-1} \partial_{y}^{j^{\prime}}\left[\sum_{j=1}^{n-j^{\prime}} a_{j j^{\prime}} \sum_{k=1}^{j}\binom{j}{k} \partial_{x}^{j-k} u \phi^{(k)}\right]
$$

Since all the derivatives of $\phi$ are supported in $[R, R+1]$, let us observe that

$$
\begin{aligned}
\left|F_{1 \phi, u}\right| \leq & \max \left\{a_{j j^{\prime}}: j=1, \ldots, n ; j^{\prime}=0, \ldots, n-1\right\} \\
& \cdot \max \left\{\binom{j}{k}: j=1, \ldots, n ; k=1, \ldots, n\right\} \cdot \sum_{k=1}^{n}\left|\phi^{(k)}\right|\left|\sum_{j^{\prime}=0}^{n-1} \partial_{y}^{j^{\prime}}\left[\sum_{j=1}^{n-j^{\prime}} \sum_{k=1}^{j} \partial_{x}^{j-k} u\right]\right| \\
\leq & C \sum_{k=1}^{n}\left|\phi^{(k)}\right| \sum_{j^{\prime}=0}^{n-1} \sum_{j=0}^{n-1-j^{\prime}}\left|\partial_{y}^{j^{\prime}} \partial_{x}^{j} u\right| \leq C \chi_{[R, R+1]}(\cdot x) \sum_{j^{\prime}=0}^{n-1} \sum_{j=0}^{n-1-j^{\prime}}\left|\partial_{y}^{j^{\prime}} \partial_{x}^{j} u\right|,
\end{aligned}
$$

(here $\chi_{A}$ is the characteristic function of a set $A$ ). Then, for $\lambda>1$,

$$
\begin{aligned}
\left\|e^{\lambda x} F_{1 \phi, u}\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}^{2} & \leq C \int_{0}^{T} \int_{\mathbb{R}} \int_{R}^{R+1} e^{2 \lambda x}\left[\sum_{j^{\prime}=0}^{n-1} \sum_{j=0}^{n-1-j^{\prime}}\left|\partial_{y}^{j^{\prime}} \partial_{x}^{j} u\right|\right]^{2} d x d y d t \\
& \leq C e^{2 \lambda(R+1)} \int_{0}^{T} \int_{\mathbb{R}} \int_{R}^{R+1}\left[\sum_{j^{\prime}=0}^{n-1} \sum_{j=0}^{n-1-j^{\prime}}\left|\partial_{y}^{j^{\prime}} \partial_{x}^{j} u\right|\right]^{2} d x d y d t \\
& \leq C e^{2 \lambda(R+1)}\|u\|_{C\left([0, T] ; H^{n-1}\left(\mathbb{R}^{2}\right)\right)}^{2} \leq C e^{2 \lambda(R+1)}
\end{aligned}
$$

and $\left\|e^{\lambda x} F_{1} \pi, u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} \leq C e^{\lambda(R+1)}$, where $C=C\left(\|u\|_{C\left([0, T] ; H^{n-1}\left(\mathbb{R}^{2}\right)\right)}\right)$ is independent from $\lambda$ and $R$. Therefore

$$
\begin{aligned}
\left\|e^{\lambda x} \phi u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} & \leq\left\|e^{\lambda x} \phi u^{l} \partial_{x} u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}+\left\|e^{\lambda x} F_{1 \phi, u}\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} \\
& \leq\left\|e^{\lambda x} \phi u^{l}\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}\left\|\partial_{x} u\right\|_{L^{\infty}([R, \infty) \times \mathbb{R} \times[0, T])}+C e^{\lambda(R+1)}
\end{aligned}
$$

Using (4) we have that $\left\|\partial_{x} u\right\|_{L^{\infty}([R, \infty) \times \mathbb{R} \times[0, T])} \leq C_{1} e^{-R}$. Besides, employing the Sobolev immersion $H^{2}\left(\mathbb{R}^{2}\right) \subset L^{\infty}\left(\mathbb{R}^{2}\right)$,

$$
\begin{aligned}
\left\|e^{\lambda x} \phi u^{l}\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} & =\left[\int_{0}^{T} \int_{\mathbb{R}} \int_{\mathbb{R}} e^{2 \lambda x}|\phi u|^{2}|u|^{2(l-1)} d x d y d t\right]^{1 / 2} \\
& \leq \sup _{t \in[0, T]}\|u(t)\|_{L_{x y}^{\infty}}^{l-1}\left\|e^{\lambda x} \phi u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} \leq C\left\|e^{\lambda x} \phi u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}
\end{aligned}
$$

This way

$$
\left\|e^{\lambda x} \phi u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} \leq C_{1} e^{-R}\left\|e^{\lambda x} \phi u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}+C e^{\lambda(R+1)}
$$

Since $\phi$ is a bounded function, from the hypotheses it is clear that $\left\|e^{\lambda x} \phi u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)}<$ $\infty$. Hence, taking $R>B$ such that $C_{1} e^{-R}<1 / 2$, we obtain

$$
\left\|e^{\lambda x} \phi u\right\|_{L^{2}\left(\mathbb{R}^{2} \times[0, T]\right)} \leq C e^{\lambda(R+1)}
$$

Thus, since $\phi(x)=1$ for $x \geq 2 R$,

$$
e^{2 \lambda R}\left[\int_{0}^{T} \int_{\mathbb{R}} \int_{2 R}^{\infty}|u(t)(x, y)|^{2} d x d y d t\right]^{1 / 2} \leq\left\|e^{\lambda x} \phi u\right\| \leq C e^{\lambda(R+1)}
$$

for all $\lambda>0$, where $C$ is independent from $\lambda$. If we choose $R>1$ and let $\lambda \rightarrow+\infty$, it follows that

$$
\left[\int_{0}^{T} \int_{\mathbb{R}} \int_{2 R}^{\infty}|u(t)(x, y)|^{2} d x d y d t\right]^{1 / 2}=0
$$

Therefore $u \equiv 0$ in $[2 R, \infty) \times \mathbb{R} \times[0, T]$. Now, taking into account the symmetry of the operator $P(D)$, it is easy to see that

$$
P(D) v=\phi P(D) u+\sum_{j=0}^{n-1} \partial_{x}^{j} \sum_{j^{\prime}=1}^{n-j} a_{j j^{\prime}} \sum_{k=1}^{j^{\prime}}\binom{j^{\prime}}{k} \partial_{y}^{j^{\prime}-k} u \phi^{(k)}
$$

Then, reasoning as above, using (5) instead of (4), we can conclude that there exists $\tilde{R}>0$ such that $u \equiv 0$ in $\mathbb{R} \times[2 \tilde{R}, \infty) \times[0, T]$. Taking $R_{0}:=\max \{2 R, 2 \tilde{R}\}$, we have that $\operatorname{supp} u(t) \subset\left[-R_{0}, \times R_{0}\right] \times\left[-R_{0}, R_{0}\right]$ for every $t \in[0, T]$.
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